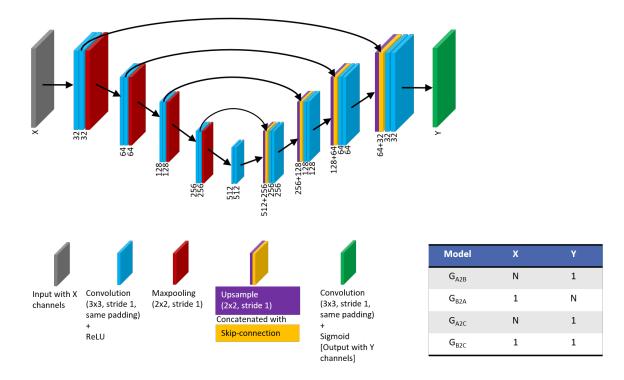
# Supplementary Material for Multi-illumination fusion with crack enhancement using cycle-consistent losses

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# **1** Network Architecture

Figure 1: Architecture used for training  $G_{A2B}$ ,  $G_{B2A}$ ,  $G_{A2C}$  and  $G_{B2C}$ .

For an input sequence having N images (N = 65 in our case), the architecture for models  $G_{A2B}$ ,  $G_{B2A}$ ,  $G_{A2C}$  and  $G_{B2C}$  is shown in Fig. 1, which is inspired from the UNet architecture [1]. The weights are initialized using Glorot Uniform initializer [2].

## 2 Initial Estimate using Modified Exposure Fusion

The exposure fusion method [3] does not enhance the image in case of pixels being underexposed in most of the images of the input sequence. This is a common problem with multi-exposure fusion (MEF) methods. In order to generate the initial estimate for training the image generators, we modified the exposure fusion method by including a preprocessing step and additional criteria for calculating the weights for fusion. These changes are discussed below.

#### 2.1 Preprocessing

Every image in the input sequence is processed independently. We start the preprocessing step by generating 18 kernels obtained by rotating a  $3 \times 3$  identity kernel in steps of 10 degrees. These kernels are used to perform morphological closing on the input image to obtain 18 feature maps. These feature maps are combined into a single map by considering the maximum value at pixel across the 18 channels. The resulting feature map is added to the input image and this operation is repeated to generate the output  $I_{out}$  as indicated by Eq. 1.

$$I_{1} = I_{in} + f(I_{in}),$$

$$I_{2} = I_{in} + f(I_{1}),$$

$$I_{out} = I_{in} + f(I_{2}),$$

$$f(I) = \max_{i=1}^{18} (I \bullet k_{i}),$$
(1)

where  $\bullet$  denotes the closing operation and  $I_{in}$  is the input image.

## 2.2 Additional Criteria

#### 2.2.1 Change across subsequently acquired images

The images are acquired in an anti-clockwise order of placement of the illumination source. Therefore, a large change in the intensity across subsequently acquired images can indicate presence of interesting details, the weightage for an image for a pixel  $I_k(x, y)$  in the image  $I_k, i \in [0, 1, ..., N]$  of the acquired sequence, the corresponding weight  $w_k(x, y)$  for this criteria is calculated as:

$$w_{k}(x,y) = \sum_{\substack{j=max(0,k-1)\\j=max(0,k-1)}}^{min(k+1,N)} |I_{k}(x,y) - I_{j}(x,y)|,$$

$$w_{k}(x,y) = \frac{w_{k}(x,y)}{\sum_{\substack{j=0\\j=0}}^{N-1} w_{j}(x,y)}.$$
(2)

#### 2.2.2 Mean based prior

If the mean intensity of the pixels in an image is close to that of a well exposed image then it should get higher weightage. Thus, the weightage used for mean based prior is

$$w_{k} = exp\left(-\frac{(avg(I_{k}) - \mu)^{2}}{2\sigma^{2}}\right),$$

$$w_{k} = \frac{w_{k}}{\sum_{j=0}^{N-1} w_{j}}.$$
(3)

where  $\mu$  is the mean and  $\sigma$  is the standard deviation of an expected well exposed image. In our implementation we have used  $\mu = 0.5$  and  $\sigma = 0.2$  with image intensities in the range [0, 1].

### 2.2.3 Contrast

In addition to the two additional criteria described above, we calculate the contrast weight using magnitude of the Sobel operators' output over a 9 neighbourhood. In the exposure fusion [3] method, this is done using the absolute value of the Laplacian operator's output over a  $3 \times 3$  neighbourhood.

## References

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